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PREFACE

The California Energy Commission Energy Research and Development Division supports public interest energy research and development that will help improve the quality of life in California by bringing environmentally safe, affordable, and reliable energy services and products to the marketplace.

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- Industrial/ Agricultural/ Water End-Use Energy Efficiency
- Renewable Energy Technologies
- Transportation

Evaluation of Numerical Weather Prediction for Intra-Day Solar Forecasting number 500-08-017 conducted by the University of California, San Diego. The information from this project contributes to Energy Research and Development Division’s Renewable Energy Technologies Program.

For more information about the Energy Research and Development Division, please visit the Energy Commission’s website at www.energy.ca.gov/research/ or contact the Energy Commission at 916-327-1551.
ABSTRACT

Numerical weather prediction models are generally the most accurate tools for forecasting solar irradiation several hours in advance. This study validated the North American Model, Global Forecast System, and European Centre for Medium-Range Weather Forecasts global horizontal irradiance forecasts against ground measurement data and persistence forecasts. All numerical weather prediction models were biased for measured clear conditions by less than 50 watts per metre² and for cloudy conditions the models were biased towards forecasting clear conditions, resulting in large, positive biases.

Mean bias errors were obtained for each numerical weather prediction model as a function of solar zenith angle and forecast clear sky index. The North American Model and Global Forecast System were positively biased by up to 150 watts per metre² for forecast clear sky conditions, while the European Centre for Medium-Range Weather Forecast mean bias errors were small. Outside of the few clear forecasts that were actually cloudy, the reason for this bias was that the Global Forecasting System and especially the North American Model forecasts can exceed clear sky irradiances by up to 40 percent, indicating an inaccurate clear sky model. For forecast cloudy conditions the North American Model and Global Forecast System models had a moderate negative bias, while European Centre for Medium-Range Weather Forecast forecasts were most biased.

Model output statistics-corrected numerical weather prediction forecasts provided important baseline accuracy for evaluating other forecasting techniques. Model output statistics minimized mean bias errors for all numerical weather prediction models. Root mean square errors were also reduced, especially for intermediate clear sky indices. The model output statistics-corrected Global Forecast System provided the best solar forecasts for the continental United States. The European Centre for Medium-Range Weather Forecast provided the most accurate forecast in cloudy conditions, while the Global Forecast System had the best clear sky accuracy.

Please use the following citation for this report:

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EXECUTIVE SUMMARY

Introduction

Accurate forecasting of solar irradiance is essential for the efficient operation of solar thermal power plants, the management of energy markets, and the widespread implementation of solar photovoltaic (PV) technology. Solar forecasts are often derived from physics-based numerical weather prediction (NWP) models.

Project Purpose

The goal of this project was to evaluate the forecast skill of NWP models by comparing several intra-day solar forecasts against ground measurements and persistence forecasts. The results were intended to provide a guideline on the maturity, applicability, and research needs related to NWP forecasting.

Project Results

Three NWP models were analyzed: the hourly North American Model (NAM) forecast, the three-hourly Global Forecast System (GFS) forecast; and the three-hourly European Center for Medium-range Weather Forecasting (ECMWF) forecast. These “raw” forecasts were compared to measurements from seven solar irradiance stations (SURFRAD) across the United States. Forecast accuracy was evaluated through the root mean square error (RMSE) and mean bias error (MBE). Subsequently, a bias correction called model output statistics (MOS) was applied to reduce persistent errors. Correction functions were fit to the observed MBE as a function of solar zenith angle and clear sky index. The accuracy of bias-corrected NWP forecasts provided a useful reference to establish the value of other more expensive or complex solar forecast products from specialized forecast providers. The results in this report will also facilitate the selection of global or national NWP models for initialization of such local models.

Table ES1 summarizes the forecast errors. For the uncorrected models, ECMWF performed best, closely followed by GFS. Surprisingly, the NAM model performed worst despite its higher spatial resolution and specialized application to North American meteorology. Significant problems were found with the NAM clear sky model, which over-predicted global horizontal solar irradiation (GHI) in clear conditions by up to 40 percent.

Table ES1: MBE and RMSE for NWP forecasts before and after MOS correction (subscript ‘c’) averaged across all sites.

<table>
<thead>
<tr>
<th></th>
<th>NAM</th>
<th>GFS</th>
<th>ECMWF</th>
</tr>
</thead>
<tbody>
<tr>
<td>MBE (W m(^{-2}))</td>
<td>57.5</td>
<td>35.4</td>
<td>31.4</td>
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<tr>
<td>MBE(_c) (W m(^{-2}))</td>
<td>7.0</td>
<td>5.2</td>
<td>0.5</td>
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<tr>
<td>RMSE (W m(^{-2}))</td>
<td>134.2</td>
<td>110.5</td>
<td>123.2</td>
</tr>
</tbody>
</table>
The MOS corrections reduced RMSE and effectively eliminated MBE. RMSE reductions were largest for partly cloudy conditions at about 50 watts per metre$^2$ (W m$^{-2}$). MOS-corrected RMSE were smallest at the sunnier sites. The GFS model was most accurate after MOS correction, indicating that its errors were more systematic.

The NWP models were shown to be significantly biased towards predicting clear skies. All models predicted more false clear days than false cloudy days. Of the forecasts that erroneously predicted clear or cloudy conditions, 78 percent of NAM, 76 percent of GFS and 64 percent of ECMWF were clear forecasts resulting in cloudy days. This was a primary contributor to the large positive MBE observed in forecast clear conditions. Although false cloudy forecast were considerably less frequent (about 6 percent for all models), far fewer cloudy days were predicted overall. These few large negative bias events account for part of the 150 W m$^{-2}$ MBE in overcast conditions for NAM and GFS.

Forecast errors can originate from a variety of sources. MOS corrections in the measured clear sky regime did not reduce RMSE because the MOS could not distinguish between errors in the clear sky models and errors related to cloud prediction. Consequently, many initially accurate forecasts were unnecessarily corrected by the MOS. Differentiating between the sources of the error was the next step in understanding which forecasts need to be corrected, which was preferable to correcting all forecasts. The relationship of MBE to other prognostic variables should be investigated, most notably those involved in cloud parameterization.

A final consideration of NWP forecasting was resolution. Even the 0.1° x 0.1° NAM spatial resolution was insufficient to resolve most clouds and only an average cloud cover could be forecasted. The resolution was even coarser for the GFS and ECMWF. Even if the spatial resolution was finer, the temporal output intervals would not permit the examination of time dependent cloud cover variability, which was important for predicting ramp rates and bands of variability for solar power plants. NWP model time-steps are on the order of minutes but radiative transfer models are run less frequently and the output was only hourly for NAM or every three hours for GFS and ECMWF. Consequently, any patterns with characteristic time scales less than an hour were unresolved.

As expected, 24-hour persistence forecasts were inaccurate except for measured clear conditions. The accuracy of one-hour persistence forecasts was comparable to bias-corrected NWP models for clear conditions, but better for cloudy conditions, especially with a clear sky index less than 0.5. A combination of GFS forecasts for clear conditions and ECMWF conditions for cloudy conditions would yield the most accurate NWP forecast product.

**Project Benefits**

This study helped advance the understanding of forecasting solar irradiance, which could help improve the efficiency of solar power plants and increase the implementation of solar PV technologies. More efficient and widespread use of solar power to generate electricity will help California meet its Renewable Portfolio Standard goals and reduce greenhouse gas emissions that contribute to climate change and other air emissions that cause air pollution.
CHAPTER 1
Introduction

Accurate forecasting of solar irradiance is essential for the efficient operation of solar thermal power plants, the management of energy markets, and the widespread implementation of solar photovoltaic (PV) technology. Early forecasting attempts used model output statistics (MOS) to establish regression models between solar irradiance measurements and available forecast variables. Subsequent forecasts of these variables were used as input to MOS, predicting solar irradiation. Using this method, Jensenius and Cotton forecasted daily global horizontal solar irradiation (GHI) on a 6 to 30-hour forecast horizon with a root mean square error (RMSE) of 13.2 percent of extraterrestrial radiation received.

Similarly, artificial neural networks (ANNs) recognize patterns in data by mimicking the logical processes of a biological neural network and have been successfully applied to solar forecasting. Using training data, typically years of measured ground data, ANNs have been developed to reduce overall relative RMSE (rRMSE) of GHI by as much as 15 percent when compared to 12 to 18-hour ahead NWP forecasts.

For physically-based forecasting, cloud cover and cloud optical depth are the most important parameters affecting solar irradiance. Through processing of satellite or ground imagery, clouds can be detected, characterized, and advected to predict GHI accurately up to 6 hours in advance. Hammer et al. demonstrated 30 minute GHI forecasts accurate to within 17 percent rRMSE and 30 percent RMSE for 2-hour forecast horizons. For intra-day forecasts, a reduction in rRMSE by 7 percent-10 percent compared to persistence forecasts was found.

Forecasts beyond 6 hours, up to several days ahead, are generally most accurate if derived from numerical weather prediction (NWP). NWP models predict GHI using columnar (1D) radiative transfer models (RTM). In most existing NWP models solar irradiation is only used to force the

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average surface energy balance, making GHI variability less relevant. Consequently, computationally expensive RTMs are only run once every 30 to 60 minutes while model time-steps are on the order of one minute. Heinemann et al. showed that the MM5 mesoscale model can predict GHI in clear skies without mean bias error (MBE). However, the bias was highly dependent on cloud conditions; in overcast conditions, the MM5 model MBE was 129 percent. Perez et al. examined the accuracy of the National Digital Forecast Database (NDFD), a derivative of the operational NWP models published by the National Center for Environmental Prediction (NCEP). After a local correction function was applied, Perez et al. found that for 8 to 26-hour forecast horizons, the NDFD had a GHI rRMSE of 38 percent. This was more accurate than satellite derived forecasts for similar forecast horizons (rRMSE = 46 percent).

Due to complex cloud microphysics and limitations in spatial resolution, clouds and their radiative properties are difficult to predict in numerical models. Consequently, NWP models are expected to show inherent regional or global biases limiting forecast accuracy. Armstrong compared the Dudhia radiative model forecast GHI to a single ground measurement site and found a relationship between MBE and cloud cover. Similarly, Remund et al. examined NWP biases compared to a single site to find that European Centre for Medium-Range Weather Forecasts (ECMWF) and Global Forecast System (GFS) next day GHI forecasts have an MBE of 19 percent. This MBE was shown to be approximately constant for intra-day (hour-ahead) to 3 day ahead forecast horizons. Breitkreuz et al. included aerosol effects on irradiance into the ECMWF model to show a reduction in GHI rRMSE for 2 to 3 day ahead forecasts from 11.5 percent to 7.2 percent under clear sky conditions. Similarly, rMBE was improved from -9.8 percent to 5.1 percent.

Consistent error patterns allow for MOS to be used to produce a bias reduction function for future forecasts. Bofinger and Heilscher used MOS locally with ECMWF GHI forecasts to create daily solar electricity predictions accurate to 24.5 percent RMSE. Lorenz et al. related forecasted solar zenith angle (SZA) and clear sky index (kt, Eq. 2) to ECMWF MBE for Germany, revealing a consistent over prediction (up to 100 W m$^{-2}$) for moderately cloudy conditions.

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9 Armstrong, M. 2000. Comparison of MM5 forecast shortwave radiation with data obtained from the atmospheric radiation measurement program. Master of Science Scholarly Paper, University of Maryland, USA.


conditions. Using a MOS correction function eliminated bias and reduced RMSE by 5 percent for 24 h forecasts.

This paper focuses on the analysis and MOS correction of GHI forecasts from three operational NWP models within the continental United States (North American Model, NAM, GFS, and ECMWF; Section 2). A fourth operational NWP model, the Rapid Update Cycle (RUC), was not evaluated. The approach presented here expands upon previous work. Remund et al.\textsuperscript{15} compared six months of ECMWF, NDFD, and GFS-WRF forecasts against three ground measurement sites. Furthermore, bias reducing MOS corrections were not examined. Additionally, Perez et al.\textsuperscript{16} evaluated the NDFD at a single site. There, however, the MOS approach was based on cloud cover parameters and not irradiance. For this paper, all available operational NWP models (Section 2) are validated against a nationwide network of meteorological stations for up to 1 year. The MOS correction function is established directly from the NWP model output for solar radiation. Consistent biases are shown as a function of measured (Section 4.1) and forecast clear sky index (Section 4.2) motivating the application of a MOS correction as a function of solar zenith angle and clear sky index. Implementation of the MOS correction mitigates bias errors of the NWP forecasts and significantly reduces RMSE (Section 4.3). Finally, it is concluded (Section 5) that MOS corrections lead to more accurate prediction of solar irradiance, given a location, time, and basis forecast model. Only intra-day (or hour-ahead) forecasts are considered since NWP forecast accuracy has been shown to be approximately constant over a 3 day horizon\textsuperscript{15} and intra-day forecasts are relevant for energy markets.


CHAPTER 2:
Numerical Weather Prediction and Ground Validation Data

2.1 North American Mesoscale Model (NAM)

The NAM forecast is published by the National Oceanic and Atmospheric Administration’s (NOAA) NCEP on a 0.113° E-W by 0.111° N-S (approximately 12 km x 12 km) grid spanning the entire continental United States (CONUS, Fig. 1, Table 1). Hourly output, available up to 36 hours ahead, is published four times daily at 00, 06, 12, and 18 UTC. Additionally, the NAM forecast is available up to 84 hours ahead for a 3-hour temporal resolution. The NAM forecast is a product of the Weather Research and Forecasting – North American Mesoscale (WRF-NMM) model. Further details on the numerical model and parameterization methods are available in Skamarock17.

Among over 125 output variables, total downward short wave radiation at the surface (Fig. 1) is reported. This is equivalent to global horizontal irradiance (GHI) or the total amount of radiation, direct and diffuse, incident on a horizontal surface at the earth’s surface. Downward shortwave radiation is a non-native forecast parameter that is calculated from several radiative transfer models: A derivative of the Eta Geophysical Fluid Dynamics Laboratory shortwave model18 (GFDL-SW); the Dudhia19 shortwave model as used by MM5; or the Goddard20 shortwave model17. The operational NAM model analyzed here use the GFDL-SW model. Using the principle of multiple scattering and Mie theory, the GFDL-SW model assumes that the primary source of radiative absorption, reflection, and scattering in the atmosphere is from concentrations of large particles such as water droplets in clouds. Cloud optical depth and albedo are parameterized using a separate cloud model and are based on prognostic numerical variables such as water mixing ratios (liquid and ice), temperature, and pressure21. Ozone and carbon dioxide concentrations from climatological tables are used. Radiative transmission is subsequently calculated in an assumed plane-parallel atmosphere with homogeneous layers.

The GFDL-SW model is strictly one-dimensional, i.e. GHI is only affected by conditions present in the column of atmosphere directly above the grid point\textsuperscript{23}.

Figure 1: NAM GHI Forecast [W m\(^2\)] for April 10th, 2010 at 2000 UTC for the NAM domain over North America. Triangles show SURFRAD stations.

Table 1: NWP Forecast Summary

<table>
<thead>
<tr>
<th></th>
<th>NAM</th>
<th>GFS</th>
<th>ECMWF</th>
</tr>
</thead>
<tbody>
<tr>
<td>Spatial resolution</td>
<td>0.11(^\circ)</td>
<td>0.5(^\circ)</td>
<td>0.25(^\circ)</td>
</tr>
<tr>
<td>Radiative Transfer Model</td>
<td>GFDL-SW</td>
<td>RRTM-SW</td>
<td>McRad</td>
</tr>
<tr>
<td>GHI variable name</td>
<td>dswrfsvfc</td>
<td>dswrfsvfc</td>
<td>surface solar radiation downwards</td>
</tr>
<tr>
<td>Output temporal resolution/forecast horizon</td>
<td>1 h / 36 h</td>
<td>3 h / 180 h</td>
<td>3 h / 144 h; 6 h / 240 h</td>
</tr>
<tr>
<td>Temporal averaging</td>
<td>Instantaneous</td>
<td>3 h, 6 h alt.</td>
<td>3 h, 6 h, 9 h, etc.</td>
</tr>
</tbody>
</table>

2.2 Global Forecast System (GFS)

Unlike the NAM, the GFS is a global forecasting model. Also published by NOAA through NCEP\(^\text{24}\), the GFS model has a spatial resolution of 0.5° E-W by 0.5° N-S (Table 1). Temporally, the GFS forecast is published at 00, 06, 12, and 18 UTC, at an average time-step of 3 hours up to 180 hours (7.5 days) ahead. GFS forecasts are reported as alternating 3 (1\(^\text{st}\), 3\(^\text{rd}\), etc. forecasts in a series) and 6-hour (2\(^\text{nd}\), 4\(^\text{th}\), etc.) averages. Consistent 3-hour resolution forecasts are calculated from the raw data.

The SW radiative model employed by the GFS is the rapid radiative transfer model\(^\text{25}\) (RRTM-SW). RRTM uses the correlated-\(k\) method to transform the spectral dependence of radiative absorption coefficients (\(k\)) into a continuous cumulative distribution function. The transformed space is subsequently discretized and characteristic \(k\) values calculated for each sub-interval. Using a two-stream adding method, radiative transfer calculations are performed independently for each sub-interval across all vertical layers. This is similar to the individual spectral-point line-by-line radiative transfer model\(^\text{27}\) (LBLRTM) calculations.

Absorption effects from water vapor, ozone, oxygen, and methane are considered. Additionally, cloud optical depth, albedo, asymmetry factor, and effective particle radius contribute to layer radiative properties. Similar to the Stephens\(^\text{28}\) parameterization, cloud properties are largely dependent on liquid water path (LWP), ice water path (IWP), temperature, pressure, and location\(^\text{29}\).

2.3 European Centre for Medium Range Weather Forecasts (ECMWF)

Like the GFS, the ECMWF is a global forecast model. Spatially, ECMWF data is available on a 0.25° E-W by 0.25° N-S grid (Table 1). Temporally, ECMWF forecasts have a time-step size of 3 h and are published twice daily (00 UTC and 12 UTC) up to 10 days in advance. Data is published as progressive averages (i.e. 3 h, 6 h, 9 h, etc.) for each series. From this, 3-hour resolution forecasts are calculated. For this study, only intra-day forecasts were considered (24-hour forecast horizon). Downward surface solar radiation data released at 12 UTC between September 1\(^\text{st}\), 2009 and August 31, 2010 were purchased.


The current operational ECMWF model contains the McRad radiation model. The shortwave portion of McRad is based on RRTM. Constituents accounted for in McRad are water vapor, carbon dioxide, ozone, methane, nitrous oxide, aerosols, and various chlorofluorocarbons (CFCs). Similar to the GFDL-SW model, important forecast cloud properties are albedo and optical depth and are parameterized primarily from LWP and effective droplet radius (Table 3 in Morcrette et al.). From the radiative properties, a two stream adding method is used to solve the radiative model at each level, resulting in surface GHI.

2.4 SURFRAD Ground Measurement Network

Seven Surface Radiation Budget Network (SURFRAD) stations across the CONUS provide an accurate nationwide database to validate NWP forecasts (Fig. 1). SURFRAD stations are equipped with Eppley Precision Spectral Pyranometers (PSP) capable of measuring GHI to within ±2 percent. The PSPs are calibrated through NOAA’s Solar Radiation Facility. One minute GHI is reported as an average of sixty 1-sec instantaneous measurements. Due to pyranometer thermal offset, night time GHI values are generally negative. For this reason, all negative values of GHI were set to zero. Data flagged by the baseline quality control (QC) assessment function due to historically inconsistent, unphysical, and uncharacteristic data were removed from this analysis. SURFRAD GHI data were aggregated to one hour averages for comparison with the (hourly or longer) output time-step of NWP forecasts.

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CHAPTER 3: Forecasting Methods

3.1 Forecasting Methods

Fig. 2 depicts a sample time series of the forecast methods that will be evaluated. The most basic "forecast", \( C \), is the Ineichen clear sky model\(^{35}\). \( C \) primarily depends on location, time, and elevation. Additionally, \( C \) is dependent on atmospheric turbidity variations due to aerosols, ozone, and water vapor, which are input as monthly averages of the Linke turbidity from the SoDA database on an 8 km grid\(^{35}\).

![Figure 2: GHI forecasts compared against Desert Rock, NV SURFRAD ground measurements on July, 17\(^{th}\) 2010. N: linear interpolated NAM; \( N_K \): clear sky index interpolated NAM; \( G \): GFS three hour constant clear sky index; \( E \): ECMWF three hour constant clear sky index; \( P \): persistence; \( C \): clear sky forecast.](image)

The persistence forecasts, \( P \), and \( P_{24} \), assume static weather conditions. The measured clear sky index \((kt_m)\) is defined as the ratio of measured GHI to \( C \),

\[
kt_m = \frac{GHI_{MEAS}}{GHI_{ck}} \tag{Eq. 1}
\]

\( P_{24} \) forecasts GHI by assigning the \( kt_m \) at solar noon of the previous day to the entire intra-day forecast \((kt_p)\). \( P_{24} \) is calculated by multiplying \( kt_p \) with the clear sky model, \( C \). The 1 hour

Persistence forecast, \( P_1 \), is calculated by multiplying \( k_{t}\) \((\text{the measured clear sky index averaged over the previous hour})\) with \( C \). In this way, \( P_1 \) is a ‘best-case’ persistence forecast for hour-ahead forecasting, while \( P_{24} \) is a typical persistence forecast for day-ahead forecasting.

Forecasts originating shortly before the CONUS sunrise are the timeliest for planning intra-day power plant load-following. Thus, the only NWP forecasts (Sec. 2.1-2.3) considered for this study originate at 1200 UTC. As NWP forecast errors have been shown to be constant over a forecast horizon of 1 hour to 3 days\(^{30}\), the results of this paper can also be considered applicable to day-ahead (i.e. next day) forecasts.

Interpolation of NWP output is necessary to temporally align NWP output and ground measurement data. Since sun position and solar zenith angle are non-linear functions of time, solar irradiance cannot be a linear process. Therefore, linear interpolation of GHI is inappropriate \((N, \text{Fig. 2})\). Instead, clear sky index \( k^* \) interpolation should be used

\[
kt_m = \frac{\text{GHI}_{\text{MEAS}}}{\text{GHI}_{\text{CSK}}}
\]

(Eq. 2)

Where GHI\(_{\text{CSK}}\) is calculated from \( C \). \( k^* \) is then interpolated to time \( t_2 \) and the NAM forecast becomes \( N_k = k^*(t_2) \text{GHI}_{\text{CSK}}(t_2) \).

Since the clear sky model, \( C \), is nearly linear over the hourly time-step of the NAM output, \( N \) and \( N_k \) produce essentially identical forecasts (Fig. 2). \( N_k \) is the correct forecast and will henceforth be considered the primary forecasting method for the NAM model.

For the GFS and ECMWF, GHI forecasts are average irradiances applicable to the entire forecast interval. 3-hour clear sky indices are calculated through Eq. 2 and multiplied by \( C \) to produce the hourly \( G \) and \( E \) forecasts. Table 2 compares each forecasting method for a single day forecast horizon.

<table>
<thead>
<tr>
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<th>12</th>
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</tbody>
</table>

Table 2: Comparison of the forecast timesteps over a single day. Boxes represent averaging periods of constant clear sky index \( k^* \) \((kt_m \text{ for } P_1 \text{ and } P_{24})\). \( N_k \) is interpolated from hourly instantaneous values and assumed to apply over the entire hourly interval. The GFS provides a combination of 3 and 6-hour interval forecast, from which 3-hour forecasts can be back calculated (striped box).

---

3.2 Spatial Averaging

$N_k$, $G$, and $E$ are spatially discrete functions for GHI. Girodo\(^{37}\) showed that spatial averaging of ECMWF output over 0.5° x 0.5° reduces the rRMSE of NWP forecasts. Here, forecast GHI for each station is calculated by taking the mean output GHI of all NWP grid points within various distances (10 km, 50 km, 100 km, and 200 km). The mean absolute error (MAE) is not biased by large error events and is the best metric for determining the advantage of spatial averaging (Sec. 4.1).

3.3 Error Metrics

Equations 2-5 define error metrics used in NWP forecast evaluation: the mean absolute error (MAE), mean bias error (MBE), relative mean bias error (rMBE), and relative root mean squared error (rRMSE), respectively:

\[
MAE = \frac{1}{N} \sum_{i=1}^{N} |GHI_{NWP,i} - GHI_{MEAS,i}|	ag{Eq. 3}
\]

\[
MBE = \frac{1}{N} \sum_{i=1}^{N} (GHI_{NWP,i} - GHI_{MEAS,i})
\]

\[
rMBE = \frac{1}{N} \sum_{i=1}^{N} \frac{GHI_{NWP,i}-GHI_{MEAS,i}}{GHI_{MEAS,(SZAt^*)}}
\]

\[
rRMSE = \sqrt{\frac{1}{N} \sum_{i=1}^{N} \left(\frac{GHI_{NWP,i}-GHI_{MEAS,i}}{GHI_{MEAS,(SZAt^*)}}\right)^2}.	ag{Eq. 6}
\]

Relative errors are obtained by normalizing to the mean measured global horizontal irradiance ($GHI_{MEAS}$) as a function of solar zenith angle (SZA) and clear sky index. Through the use of this time and measurement dependent normalization, as opposed to constant as in many other validation studies (e.g. Lorenz\(^{38}\)), mid-day relative errors are reduced through normalization and early morning/ late evening errors are amplified. As errors will be considered as a function of $kt^*$ and SZA, this normalization provides a metric relevant to the period over which the error is calculated.

3.4 MOS Correction

Following Lorenz\(^{38}\) a stepwise multivariate fourth-order regression\(^{39}\) is applied to derive the MOS correction function.

\[
GHI_c(SZA,kt^*) = \alpha \cos^4(SZA) + \beta (kt^*)^4 + \ldots
\]  \tag{Eq. 7}


GHI<sub>c</sub> is the model MBE for a given SZA and clear sky index. Weighted regression coefficient calculation ensures accurate representation of unevenly distributed data (see Fig. 5). For all combinations of SZA and \( kt^* \), GHI<sub>c</sub> provides the best irradiance correction for any future forecast. As an example, the MOS-corrected NAM forecast, \( N_{K,c} \), is computed as

\[
N_{K,c} = N_K - GHI_c
\]  

(Eq. 8)

To simulate operational forecasting, local MOS correction functions are calculated dynamically using only the most recent 56 days of MBE analysis (rather than the entire dataset) separately for each SURFRAD station. This provides a training dataset, independent of the evaluation dataset, and a unique MOS correction for each \( N_{K,c} \). This method is similarly applied for \( G \) and \( E \) and designed to eliminate systematic bias error. Since MOS corrections are not applicable for SZAs larger than 75°, evening and early morning corrected forecasts are not calculated.
CHAPTER 4:
Results

4.1 Numerical Forecast Evaluation

4.1.1 Effect of Spatial Averaging – Mean Absolute Errors
Spatial averaging of the $N_k$ (Fig. 3) and $G$ (not shown) forecasts results in a reduction in MAE. As the scale of spatial averaging increases, the MAE across the majority of measured clear sky indices decreases. Only for small measured clear sky indices ($k_t < 0.25$) does MAE increase with increased spatial averaging, especially for the 200 km spatial averaging radius. Girodo\textsuperscript{40} and Lorenz et al.\textsuperscript{41} also found reduced errors for averaging over a 100 km x 100 km square grid for the ECMWF forecast. Henceforth, only the 100 km radius spatial average will be considered for the analyses.

![Figure 3: $N_k$ MAE (W m$^{-2}$) as a function of measured clear sky index ($k_t$) for different averaging radii of the NAM model. 50, 100, and 200 km averaging radii correspond to approximately 80, 300, and 1250 grid points, respectively.](image)


4.1.2 Mean Bias Errors of N<sub>k</sub>, G and E forecasts

Fig. 4 reveals similar MBE profiles for each NWP model. Given measured clear conditions and SZAs near solar noon, all NWP forecasts are negatively biased by between 0 and 50 W m<sup>-2</sup> (Fig. 4), indicating the presence of cloudy forecasts that resulted in clear periods. These results may be biased by location and season, since northern stations experience a cos(SZA) > 0.9 only for a short part of the year.

![Figure 4](image)

**Figure 4**: NWP forecast MBE (W m<sup>-2</sup>) as a function of SZA and measured clear sky index for all SURFRAD stations for a) N<sub>k</sub>; b) G; c) E.

In clear skies, MBE increases with SZA reaching 50 W m<sup>-2</sup> for cos(SZA) = 0.35 for N<sub>k</sub> and approximately 0 W m<sup>-2</sup> for G and E. At cos(SZA) < 0.4, many N<sub>k</sub> forecasts predict up to 40 percent more GHI than clear sky models (kt* = 1 to 1.4, see Fig. 5a). This over-prediction of GHI in measured clear conditions is surprising as it potentially indicates an inaccurate NWP clear sky model.
For measured cloudy conditions \((kt_m < 0.8)\) and relevant SZA (SZA < 75°), \(N_k\), \(G\), and \(E\) are positively biased by up to 225 W m\(^{-2}\). Positive MBEs in measured cloudy conditions \((kt_m < 0.8)\) suggest that either cloudy conditions were not predicted or that the prescribed cloud optical depths or cloud cover fractions were too small.

Some of these patterns can be explained by the binary nature (either cloudy or clear) of solar forecasts. Examination of the data distribution of predicted and measured conditions (Table 3 with an overcast threshold of \(kt = 0.8\)) shows that 20.6 percent of all \(N_k\) forecasts are measured cloudy days which were predicted to be clear. False clear forecasts occurred in 19.7 percent of \(G\) forecasts and 12.4 percent of \(E\) forecasts. Forecast cloudy, but measured clear conditions were only observed for 5.7 percent \((N_k)\), 5.5 percent \((G)\), and 6.9 percent \((E)\) of forecasts. These results are indicative that the NWP models are generally biased towards predicting clear conditions and at a larger clear sky index than measured. Overall, the ECMWF model had the smallest likelihood of incorrect forecasts (19.3 percent) while both the NAM and GFS were incorrect for 25 percent of forecasts.

<table>
<thead>
<tr>
<th>SURFRAD</th>
<th>(N_k) Cloudy</th>
<th>(N_k) Clear</th>
<th>(G) Cloudy</th>
<th>(G) Clear</th>
<th>(E) Cloudy</th>
<th>(E) Clear</th>
</tr>
</thead>
<tbody>
<tr>
<td>Cloudy</td>
<td>0.187</td>
<td>0.206</td>
<td>0.170</td>
<td>0.197</td>
<td>0.282</td>
<td>0.124</td>
</tr>
<tr>
<td>Clear</td>
<td>0.057</td>
<td>0.550</td>
<td>0.055</td>
<td>0.579</td>
<td>0.069</td>
<td>0.525</td>
</tr>
</tbody>
</table>

### 4.2 MOS Correction of Forecast Mean Bias Errors

#### 4.2.1 \(N_k\) Forecast

Fig. 5a is the histogram for the NAM forecast between March 21\(^{st}\), 2010 and February 8\(^{th}\), 2011, as a function of SZA and \(kt^*\). Consistent with Table 3, more data exist for predicted clear skies than for cloudy conditions. Fig. 5a indicates that the NAM model often forecasts GHI 20 percent to 40 percent in excess of clear sky irradiance, especially for large SZA. While low atmospheric turbidity during clear sky conditions can result in GHI measurements slightly larger than \(C\), the frequency and magnitude of forecasts with \(kt^* > 1\) indicates a fundamental problem with either the NAM radiative transfer model or the primary inputs to the model from the NAM forecast. \(G\) forecasts only exhibit \(kt^* > 1\) for SZA greater than 75°, which could be caused by a different choice of clear sky model. \(kt^* > 1.1\) are not observed for \(E\) forecasts.

The MBE profiles in Fig. 4 demonstrate consistent MBE patterns. However, \(kt_m\) is unknown prior to measurement and is unsuitable as an input parameter for MOS correction. Instead MBE profiles as a function of the predicted clear sky index, \(kt^*\) must be used. Fig. 6a shows the MBE of the \(N_k\) forecast as a function of \(cos(SZA)\) and \(kt^*\). For forecast clear sky conditions \((kt^* > 0.8)\), \(N_k\) over-predicts measured data by up to 150 W m\(^{-2}\) and on average by 73.9 W m\(^{-2}\). In cloudy conditions \((kt^* < 0.5)\), the \(N_k\) model under-predicts measured GHI, on average by -32.3 W m\(^{-2}\). Overall, the magnitude of the negative MBE becomes larger for small SZA, while the positive MBE for clear sky conditions becomes slightly smaller for small SZA.
While $N_x$ is an overall inaccurate GHI forecast, Fig. 6a shows that NAM bias trends are continuous and therefore, correctable. Using MOS (Sec. 3.4), a correction polynomial was fit to the data (e.g. Fig. 6b). Fig. 6b well represents the typical MBE characteristics of $N_x$. Corrections are subsequently applied according to Eq. 8, yielding $N_{x,c}$. Note that as temporally dynamic local MOS corrections (Sec. 3.4) were applied to simulate operational conditions, Fig. 6b was not directly used in forecast correction. The MBE of $N_{x,c}$ (Fig. 6c) decreases to less than $\pm 50 \text{ W m}^{-2}$ and overall from 57.5 W m$^{-2}$ to 7.0 W m$^{-2}$. For a perfect MOS correction, a zero MBE would be expected for $N_{x,c}$. Here, the MBE is not zero is due to the polynomial fit MOS correction which cannot fully resolve the variability of Fig. 6a.

Figure 5: Histogram as a function of solar zenith angle (SZA) and clear sky index ($kt^*$) for a) $N_x$; b) $G$; c) $E$. Data is presented in log$_{10}$ format, i.e. a value of 2 indicates 100 observations. All data to the left of the black line (SZA > 75°) were not used in the MOS analysis.
Figs. 6, 7, 8: MBE (W m\(^{-2}\)) of \(N_K\) (Fig. 6), \(G\) (Fig. 7), and \(E\) (Fig. 8), as a function of solar zenith angle (SZA) and forecasted clear sky index (\(kt^*\)) compared to SURFRAD measurements: a) raw data, b) polynomial fit to the data (Eq. 7); c) MBE of the corrected forecasts: \(N_{K,c}\), \(G_c\), and \(E_c\).

4.2.2 G Forecast

Fig. 7a shows the average MBE profile for the GFS forecast, \(G\). The bias error dependence on \(kt^*\) is qualitatively similar to the NAM model (Fig. 6a). For forecasted clear sky conditions (\(kt^* > 0.8\)), \(G\) generally over-predicts GH1, on average by 41.0 W m\(^{-2}\). Similarly, for overcast conditions with moderate to small optical depths (\(kt^* < 0.5\)), the GFS forecast is negatively biased by on average -1.8 W m\(^{-2}\). The MBE shows a much stronger dependence on SZA compared to the NAM model, increasing during mid-day (\(MBE_{AVG} = -67.4\, \text{W m}^{-2}\) for \(\cos(SZA) > 0.7\) and \(kt^* < 0.5\)) as a result of the larger GH1 magnitudes observed then.

Fig. 7b shows the MOS correction function fit to Fig. 7a for the entire data set. From Eq. 7, the MOS function applies a negative correction to \(G\) for predicted clear skies (\(kt^* > 0.8\)). Correspondingly, a large positive correction is applied for forecast overcast conditions (\(kt^* < 0.5\)). On average, the MBE of the MOS-corrected forecast, \(G_c\) (Fig. 7c) is reduced from 35.4 W m\(^{-2}\) to 5.2 W m\(^{-2}\).

4.2.3 E Forecast

The MBE profile of \(E\) (Fig. 8a) is significantly different than \(N_K\) or \(G\). Predicted clear skies (\(kt^* > 0.9\)) and overcast conditions with \(kt^* < 0.2\) are least biased (MBE < 50 W m\(^{-2}\)). For predicted moderately cloudy conditions \(E\) is most significantly biased, by 42.6 W m\(^{-2}\) on average. While there are several areas of negative bias, the MBE is in general positive, with some biases.
exceeding 150 W m$^{-2}$. Lorenz et al.\textsuperscript{42} found a similar MBE profile for ECMWF data using ground measurements in Germany.

The MOS correction function for $E$ (Fig. 8b) targets the large positive bias for moderately cloudy conditions. It should be noted that the negative bias correction for very small predicted clear sky indices ($kt^* < 0.2$) is an artifact of the correction polynomial, which is irrelevant as no such data occurred. This was also observed in the MOS function for $G$ (Fig. 7b). The MOS correction reduces overall MBE from 31.4 W m$^{-2}$ to 0.5 W m$^{-2}$ (Fig. 8c). Using this metric, the MOS correction for $E$ is the most effective in reducing systematic errors.

Figure 9: RMSE (W m$^{-2}$) as a function of measured clear sky index ($kt_m$): a) ($N_K$, $G$, $E$, $P_{1}$, $P_{24}$, and $C$); b) ($N_{K,c}$, $G_c$, $E_c$, $P_{1}$, $P_{24}$, and $C$); c) Change in RMSE due to MOS correction.

4.3 Root Mean Square Errors

For $kt_m = 1$, C is expected to have an RMSE = 0 W m$^{-2}$. For $kt_m > 0.86$, C indeed has the smallest RMSE. However, several instances of $kt_m > 1$ were observed, contributing to the non-zero RMSE for $kt_m = 1$. For overcast conditions, the RMSE of C drastically increases.

$P_1$ is the most accurate forecast for overcast conditions and only slightly less accurate than $G$ and $E$ for clear conditions. Since hourly cloud cover conditions are relatively static the one-hour persistence forecast, $P_1$, is accurate. For longer persistence forecasting on the order of a day ($P_2$), clear conditions are more static than cloudy. Correspondingly $P_2$ RMSE increases with decreasing $kt_m$, approaching a RMSE greater than 400 W m$^{-2}$ for $kt_m < 0.15$. Transitional periods between synoptic weather patterns and diurnally driven phenomena cause large errors in 24-hour persistence forecasts. For moderate cloudy conditions, the measured clear sky index can vary significantly, making the persistence forecasts inaccurate (e.g. Fig. 2 from 1800-2400 UTC).

The high spatial variability of irradiance during cloudy conditions is difficult to forecast by NWP. Consequently, NWP RMSE (Fig. 9a) increases as $kt_m$ decreases. Under measured clear sky conditions, all NWP forecasts have low RMSE (RMSE < 125 W m$^{-2}$). In clear conditions ($kt_m = 1$), $G$ is the most accurate. Excluding clear conditions, $E$ has a lower RMSE than other NWP forecasts with typical improvements of 30 W m$^{-2}$ compared to $N$ and $G$.

After MOS correction (Fig. 9b) the same general trends for NWP RMSE are present, albeit at a smaller RMSE level. The impact of MOS on RMSE is shown in Fig. 9c. Positive changes represent increases in RMSE. The RMSE of the NAM forecast $N_{k_c}$ is reduced by up to 50 W m$^{-2}$ for $0.15 < kt_m < 0.95$. Similarly, $G_c$ is improved over all clear sky indices less than 0.9 by as much as 110 W m$^{-2}$. The RMSE of $E$ is also significantly lowered for all clear sky indices less than 0.7. For the largest clear sky indices ($kt_m > 0.94$), MOS corrections increased the RMSEs for each NWP forecast. Uncorrected forecasts for measured clear conditions (Fig. 4) were relatively unbiased making it difficult to reduce RMSE. For all other clear sky indices, the MOS correction function significantly reduced RMSE.
CHAPTER 5: Summary and Conclusions

In this study, five primary intra-day forecasts were analyzed: The Ineichen clear sky model, \( C \); the persistence forecasts, \( P_1 \) and \( P_{24} \); the clear sky index (\( kt^* \)) interpolated NAM forecast, \( N_k \); the 3-hour constant \( kt^* \) GFS forecast, \( G \); and the 3-hour constant \( kt^* \) ECMWF forecast, \( E \). It is of interest to compare bias-corrected NWP model forecasts to other more advanced products such as NDFD, satellites, sky imagers, or forecasts by specialized renewable energy forecast providers. While other derived forecast products may be more accurate, the accuracy of bias-corrected NWP forecasts provides a useful reference to establish the value of other (more expensive) products.

Forecast accuracy was evaluated through RMSE and MBE. 24-hour persistence and clear sky forecasts (\( P_{24} \) and \( C \)) were inaccurate except for measured clear conditions (Fig. 9) and should be used only as baseline forecasts. The accuracy of 1-hour persistence forecasts is comparable to NWP models for clear conditions, but better for \( kt_m < 0.5 \).

The method presented by Lorenz et al.\(^{43} \) and known as model output statistics (MOS) was employed to reduce MBE in forecasted GHI. To determine forecast accuracy, it was necessary to differentiate between MBE as a function of measured clear sky index (\( kt_m \)) and forecasted clear sky index (\( kt^* \)). NWP models were validated using \( kt_m \), while MOS necessitated the use of the forecast variable, \( kt^* \). Using fourth order multivariate regression, correction functions were fit to the observed MBE as a function of solar zenith angle (SZA) and clear sky index (\( kt^* \)). Table 4 summarizes the results of the MOS correction when averaged across all SURFRAD stations. Errors separated by station are provided in Table 5 of Appendix B and are consistent with the overall errors listed in Table 4. The local MOS functions, used in conjunction with forecast SZA and \( kt^* \), reduced RMSE by 20.1 W m\(^{-2} \) (\( N_k \)), 17 W m\(^{-2} \) (\( E \)), and 25.6 W m\(^{-2} \) (\( G \)) and effectively eliminated MBE. RMSE reductions were largest for intermediate \( kt^* \) at about 50 W m\(^{-2} \). MBEs were similar across different sites with the smallest errors at Desert Rock, NV (site with the largest \( kt_m \)) and the largest errors at Pennsylvania State University, PA (site with the lowest \( kt_m \)). MOS-corrected RMSE were smallest at the most clear site, Desert Rock, and largest at Fort Peck, Montana. For all stations, seasonal changes in bias errors limit MOS-correction accuracy. For several SURFRAD stations, MBE were observed to change significantly from month to month. As the MOS-correction uses 56 days of training data, sudden changes in MBE dependence on SZA and \( kt^* \) are not immediately represented increasing the MBE of the MOS-corrected forecasts.

For the original models, ECMWF performed best, closely followed by GFS. Surprisingly, the NAM model performed the worst despite its higher spatial resolution and specialized application to North American Meteorology. Significant problems were found with the clear sky model applied in \( N_k \) which over-predicted GHI in clear conditions by up to 40 percent. After MOS correction, the GFS model was most accurate, indicating that the errors in GFS

forecasts are more systematic. A combination of GFS forecasts for clear conditions and ECMWF conditions for cloudy conditions may yield the lowest overall RMSE (Fig. 9b).

**Table 4: MBE and RMSE for NWP forecasts before and after MOS correction averaged across all sites**

<table>
<thead>
<tr>
<th></th>
<th>(N_k)</th>
<th>G</th>
<th>E</th>
</tr>
</thead>
<tbody>
<tr>
<td>MBE (W m(^{-2}))</td>
<td>57.5</td>
<td>35.4</td>
<td>31.4</td>
</tr>
<tr>
<td>(\text{MBE}_c) (W m(^{-2}))</td>
<td>7.0</td>
<td>5.2</td>
<td>0.5</td>
</tr>
<tr>
<td>RMSE (W m(^{-2}))</td>
<td>134.2</td>
<td>110.5</td>
<td>123.2</td>
</tr>
<tr>
<td>(\text{RMSE}_c) (W m(^{-2}))</td>
<td>114.1</td>
<td>84.6</td>
<td>106.2</td>
</tr>
</tbody>
</table>

The NWP models were shown to be significantly biased towards predicting clear skies. Thus, when plotted against \(kt_m\) (Fig. 4), negative biases are rare. Overall, \(N_k\), G, and E predicted more false clear days than false cloudy days (Table 3). Of the forecasts that erroneously predicted clear or cloudy conditions (Table 3), 78.3 percent of \(N_k\) (75.6 percent for G and 64.2 percent of E) were clear forecasts resulting in cloudy days. This was a primary contributor to the large positive MBE observed in forecast clear conditions (Figs. 6a, 7a, and 8a). However, the many accurate clear sky forecasts (55.0 percent of all \(N_k\), 57.9 percent of G, and 52.5 percent of E) reduced the magnitude of the MBE in clear conditions. Although false cloudy forecast were considerably less frequent (5.7 percent of all \(N_k\), 5.5 percent of G and 6.9 percent of E), far fewer cloudy days were predicted overall (Fig. 5a). These few large negative bias events account for part of the 150 W m\(^{-2}\) MBE for \(kt^* < 0.6\) for \(N_k\) and G (Fig. 6a/7a).

Evaluating ECMWF forecast accuracy in Germany, Lorenz et al.\(^{44}\) showed that NWP MBE was largest for cloudy conditions with moderate clear sky indices (0.3 < \(kt^* < 0.6\)), while forecasted clear conditions were relatively unbiased. This study revealed a similar ECMWF MBE profile for SURFRAD stations (Fig. 8a). Positively biased for moderately overcast conditions, the overall MBE of E was 31.4 W m\(^{-2}\). Consistent with the results of this study, Remund et al.\(^{45}\), found E MBEs ranging from 15 to 43 W m\(^{-2}\) at 3 different sites.

MOS application to the NWP irradiance output was successful in minimizing bias and reducing RMSE, but did not provide information as to the source of the MBE. Errors originating from the radiative transfer model (RTM), cloud model, and prognostic variable errors can all contribute to the MBE. MOS corrections in the measured clear sky regime (\(kt_m > 0.9\)) did not reduce RMSE


(Fig. 9c). This is because the MOS could not distinguish between RTM errors (over-prediction of GHI even for clear skies, especially for NAM) and cloud model errors (incorrect parameterization of RTM inputs). Consequently, many initially accurate forecasts were unnecessarily corrected. Rather than correcting all forecasts, differentiating between the sources of the error is the first step into understanding which forecasts need to be corrected. Further research will investigate the relationship of MBE to other prognostic variables, most notably those involved in cloud parameterization.

A final consideration of NWP forecasting is resolution. Even the 0.1° x 0.1° NAM spatial resolution is insufficient to resolve most clouds and only an average cloud cover can be forecasted for a given point. For the GFS and ECMWF the resolution is even coarser. However, even if the spatial resolution was finer, the temporal output intervals would not permit the examination of time dependent cloud cover variability, important in predicting ramp rates and bands of variability for solar power plants. While NWP model time-steps are on the order of minutes, the radiative transfer models are run less frequently, and the output is only hourly (NAM) or every 3 hours (GFS and ECMWF). Consequently, any patterns with characteristic time scales less than an hour are unresolved. Linking observed temporal variability in GHI to native NWP forecasts will require further research.
Appendix A:
MBE and RMSE by SURFRAD Station

MBE and RMSE before and after MOS correction. Average measured GHI and $kt_m$ are also shown.

<table>
<thead>
<tr>
<th>STN</th>
<th>NWP Model</th>
<th>MBE (W m$^{-2}$)</th>
<th>MBE$_c$ (W m$^{-2}$)</th>
<th>RMSE (W m$^{-2}$)</th>
<th>RMSE$_c$ (W m$^{-2}$)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Bondville, IL</td>
<td>$N_k$</td>
<td>59.1</td>
<td>4.6</td>
<td>137.7</td>
<td>117.0</td>
</tr>
<tr>
<td>GHI$_{avg}$ = 356.8 W m$^{-2}$</td>
<td></td>
<td>39.4</td>
<td>3.3</td>
<td>108.6</td>
<td>82.8</td>
</tr>
<tr>
<td>$kt_m$$_{avg}$ = 0.73</td>
<td></td>
<td>23.5</td>
<td>0.7</td>
<td>113</td>
<td>100.9</td>
</tr>
<tr>
<td>Desert Rock, NV</td>
<td>$N_k$</td>
<td>41.0</td>
<td>10.6</td>
<td>93.5</td>
<td>81.6</td>
</tr>
<tr>
<td>GHI$_{avg}$ = 474.7 W m$^{-2}$</td>
<td></td>
<td>18.2</td>
<td>3.2</td>
<td>83.2</td>
<td>76.9</td>
</tr>
<tr>
<td>$kt_m$$_{avg}$ = 0.87</td>
<td></td>
<td>22.3</td>
<td>1.4</td>
<td>96.4</td>
<td>87.8</td>
</tr>
<tr>
<td>Fort Peck, MT</td>
<td>$N_k$</td>
<td>53.1</td>
<td>11.8</td>
<td>124.1</td>
<td>104.5</td>
</tr>
<tr>
<td>GHI$_{avg}$ = 319.9 W m$^{-2}$</td>
<td></td>
<td>32.4</td>
<td>10.7</td>
<td>98.8</td>
<td>74.7</td>
</tr>
<tr>
<td>$kt_m$$_{avg}$ = 0.73</td>
<td></td>
<td>26.8</td>
<td>4.1</td>
<td>121.4</td>
<td>107.9</td>
</tr>
<tr>
<td>Goodwin Creek, MS</td>
<td>$N_k$</td>
<td>52.9</td>
<td>1.2</td>
<td>144.0</td>
<td>125.4</td>
</tr>
<tr>
<td>GHI$_{avg}$ = 391.3 W m$^{-2}$</td>
<td></td>
<td>36.4</td>
<td>7.1</td>
<td>122.7</td>
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<td>10.8</td>
<td>-0.9</td>
<td>127.9</td>
<td>109.8</td>
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<td>$N_k$</td>
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<tr>
<td>GHI$_{avg}$ = 314.1 W m$^{-2}$</td>
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<tr>
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<td>62.6</td>
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